Kevin Chen

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EDUCATION

Northwestern University | Evanston, IL

BS: Mechanical Engineering, Minor in Data Science and Environmental Policy

• GPA: 3.81 / 4.00

Relevant Coursework: Static & Dynamic Systems, Fluid Mechanics, Thermodynamics, Design & Manufacturing, Material Mechanics, Electronics Design, Heat Transfer, Propulsion Systems, Control Systems, Differential Equations, Multivariable Calculus, Linear Algebra, Machine Design and Dynamics, Stress Analysis, Mechanical Vibrations, Data Visualization

TECHNICAL SKILLS

- Programming (MATLAB, Python, CSS, HTML) | CAD & FEA (SOLIDWORKS, NX, Creo, Abagus, Ansys, Femap/Nastran)
- Oscilloscopes and breadboarding (nScope) | Confocal, SEM, and high-speed imaging (ImageJ, Phantom Camera Control)
- Mill and lathe (Conventional & CNC Machining) | Manufacturing (Additive, Forging, Casting, Forming, Injection Molding) •

EXPERIENCE

Sierra Space Manufacturing & Stress Analysis | Denver, CO

Technical Intern

- Conducting sine-vibration analysis through Femap & NX Nastran of the Dreamchaser and Cargo Module during ascent to validate component integrity and envelope support-structure interactions
- Proposed and tested new operable thermal margins for external cargo interface in conjunction with NASA ISS mating team
- Conducted purging operations for Dreamchaser bipropellant peroxide and kerosene tanks as well as non-destructive proof • and leak testing before orbital weld installation and X-ray inspection

NASA Langley Research Center Structural Dynamics & Testing | Hampton, VA

Structural Dynamics Intern

- Conducted flexural testing of Advanced Composite Solar Sail System (ACS3) composite booms and cube-sat assembly to insure stability of flight article for March launch on a Rocket Lab Electron vehicle
- Designed crushable hybrid composite-polymer energy absorbers in Creo Parametric and used additive manufacturing techniques to improve occupant safety by 23% during crashes within an experimental VTOL aircraft
- Diagnosed and repaired material extrusion, PBF, and SLA 3D printers (Prusa, FormLabs, Raise3D, Ultimaker, Zortrax) in ٠ rapid prototyping lab to support ACS3 evaluation and Mars Sample Return gantry testing

Northwestern University Bazant Materials Science Laboratory | Evanston, IL

Undergraduate Researcher

- Performed fracture analysis on composites, shale, and concrete to determine material properties for manufacturers
- Developed biaxial tension-compression model through SOLIDWORKS and stress analysis with Abaqus FEA
- Gained conventional & CNC machining certification using mill, lathe, drop saw, diamond-edged band saw, waterjet, etc.

NUSolar & Northwestern Formula Racing | Evanston, IL

Chassis Team Member

- Assisted manufacturing of Solar Car 7 and contributed to development of Solar Car 8 floorboard through Siemens NX modeling and Abagus FEA as an independent project with NUSolar leadership
- Specialized in composite layups, waterjet cutting, and laser cutting for current Formula vehicle pedalbox

LEADERSHIP

VEX Robotics Team, 7701X | Design and Build Lead

- 2019 & 2020 World Championship Divisional 1st place and finalists, 2019 1st place World Driver Skills Ranking, VEX Robotics 2020 National Signature Event Tournament Champion, 8x Regional Tournament Champions
- Constructed mechanisms (ratcheting rack & pinion launcher, differential 1:3 drivetrain), improved sensor suite (ultrasonic, IMU, shaft-encoder), 3D-printed custom gears and joints for lift and drive system, and upgraded pneumatics systems
- Applied PID controllers as well as odometry for autonomous motion and position tracking of robot, enabling a nearly flawless in-game autonomous route and lead 7701X to become the highest scoring team in the world during 2020

PROJECTS

L1 High Powered Rocketry Certification | National Association of Rocketry & NUStars

- Assembled LOC Precision PK-56 model rocket (F20-4W motor) to gain L1 HPR certification during 2023 winter quarter
- Proposing early stage hybrid propellent rocket engine P&ID and constructing preliminary test stands

Anvil Arrow RC Plane Replica | Personal Project

- Modeled and drafted original RC model of Star Citizen's Anvil Arrow in Siemens NX and performed stress analysis to identify potential failure modes using classical and computational methods through Ansys
- Designed fully autonomous flight system with waypoint following capabilities utilizing GPS for location data, an IMU for relative motion and orientation, servos to power control surfaces, and a brushless DC motor for propulsion
- Adapting control algorithms like LQR for stable flight and odometry for position referencing between GPS updates

Februrary 2023 - Present

December 2022 - February 2023

May 2021 - June 2022

August 2017 - May 2020

September 2020 - June 2022

September 2020 - June 2024

June 2023 - September 2023

June 2022 - September 2022